Shunya Tadano

Building-M.A.E. 523, 6-6-01 Aoba, Aramaki, Aoba-ku, Sendai, Miyagi, Japan, 980-8579 Graduate School of Engineering, Tohoku University

Research Interests

Robotics, Human-Robot Interaction, Computer Vision, Social Navigation, Gaze Estimation

Education

Tohoku University, Graduate School of Engineering

Sendai, Japan

Ph.D. Course in Robotics

April 2025 - Present

Research focus: Social navigation systems for human-robot interaction in crowded environments.

Advisor: Assoc. Prof. Yusuke Tamura

Tohoku University, Graduate School of Engineering

Sendai, Japan

Master of Engineering in Robotics, GPA: 3.7/4.0

April 2023 - March 2025

Thesis: "Pedestrian Trajectory Prediction Considering Visual Attention and Behavioral Uncertainty."

Iwate University, Faculty of Science and Engineering, GPA: 3.6/4.0

Morioka, Japan

Bachelor of Engineering in Systems Innovation Engineering

April 2019 - March 2023

Graduation Thesis: "Knife Operation Support System for Hemiplegic Patients Using Skeleton Estimation

Technical Skills

Programming Languages: Python, C++, MATLAB

Robotics Frameworks: ROS/ROS2

Simulation Tools: Gazebo

Machine Learning Libraries: OpenCV, TensorFlow

Hardware Skills: Sensors such as LiDAR, RGBD-cameras, 360 degree camera, IMUs, etc.

Other Skills: CAD software (e.g., SolidWorks, OnShape), 3D printing, navigation algorithms, etc.

Publications

- 1. **Shunya Tadano**, Yusuke Tamura, Yasuhisa Hirata, "Collision Avoidance for Mobile Robots with Attention—Aware Cost Map Generation," *The Robotics and Mechatronics Conference 2025 (ROBOMECH2025)*.
- 2. **Shunya Tadano**, Yusuke Tamura, Yasuhisa Hirata, "Posture Information Integration into Pedestrian Trajectory Prediction Considering Uncertainty," in *The Robotics and Mechatronics Conference 2024 (ROBOMECH2024)*, 2024.
- 3. Shunya Tadano, Yusuke Tamura, Yasuhisa Hirata, "Pedestrian Trajectory Prediction with Pose Estimation and Monte Carlo Dropout," in *IEEE International Conference on Robotics and Automation (ICRA2024), Late Breaking Result Poster*, 2024.

Awards

1st Prize, Japan-WIDE Sustainable Aviation Fuel and its Infrastructure Development, Boeing University Externship Summer Seminar 2024

National Runner Up, ARALA -Additive Robotic Attachment for Lab Automation-, JAMES DYSON AWARD 2024

Grants and Scholarships

2025 – 2028: AGS RISE Program Research Fellowship for Young Scientists —1,500,000 JPY 2023 – 2025: Sky Ōura ICT Scholarship Foundation Scholarship —2,000,000 JPY per year 2022 – 2023: 2022 Iwate Katada Foundation Bachelor's Thesis Research Grant —100,000 JPY 2021 – 2022: JGC • Saneyoshi Scholarship Association Stipend Scholarship —400,000 JPY

Languages

Japanese: Native

English: Intermediate(Buisiness Level)

References

Assoc. Prof. Yusuke Tamura (ytamura@tohoku.ac.jp): Associate Professor, Graduate School of Engineering, Tohoku University, Japan. (Current advisor)

Prof. Yasuhisa Hirata (yasuhisa.hirata.b1@tohoku.ac.jp): Professor, Graduate School of Engineering, Tohoku University, Japan. (Laboratory Collaborator)

MISC

- 1. 長岡瞬, **只野竣也**, 田嶋真也, 釼持優人, "学生編集委員会取材企画: リビングロボットに訊く!「あるくメカトロウィーゴ」と歩む未来," 日本ロボット学会誌, *43(4), 543-547*, 2025. (in Japanese)
- 2. 釼持優人,**只野竣也**,長岡瞬,山本晃平,"学生編集委員会取材企画:株式会社弘栄ドリームワークス「配管くん」最先端配管点検ロボットの秘密に迫る," 日本ロボット学会誌,42(6), 543-547, 2024. (in Japanese)